Math 524 Exam 6 Solutions

The first three problems all concern $A = \begin{pmatrix} -1/3 & -1/6 \\ 1/3 & -5/6 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} -1/2 & 0 \\ 0 & -2/3 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix}$

1. Solve the discrete-time system given by x(n) = Ax(n-1), with initial condition $x(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

A basis of eigenvectors is $B = \{b_1, b_2\}$, for $b_1 = (1, 1)^T, b_2 = (1, 2)^T$. We have $[x(0)]_B = {\binom{-1}{1}}$. We have $x(n) = A^n x(0) = (PDP^{-1})^n x(0) = PD^n P^{-1} x(0)$. Because $P^{-1}x = [x]_B$, we have $[x(n)]_B = D^n [x(0)]_B = D^n {\binom{-1}{1}} = {\binom{-(-1/2)^n}{(-2/3)^n}}$. Hence $x(n) = P {\binom{-(-1/2)^n}{(-2/3)^n}} = {\binom{-(-1/2)^n + (-2/3)^n}{(-(-1/2)^n + 2(-2/3)^n}}$, or $x_1(n) = (-2/3)^n - (-2)^{-n}, x_2(n) = 2(-2/3)^n - (-2)^{-n}$. One may check this with some values such as n = 0, 1, 2; or, one may check that this satisfies the difference equation and initial condition.

2. Solve the first-order system given by $\frac{d}{dt}x = Ax$, with initial condition given by $x(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

We calculate a basis of eigenvectors as before, and note that $x(0) = -b_1 + b_2$. This time $x(t) = e^{At}x(0) = e^{At}(-b_1 + b_2)$. We have $e^{At}b_1 = e^{-t/2}b_1$ and $e^{At}b_2 = e^{-2t/3}b_2$, since they are eigenvectors of A. Hence $x(t) = -e^{-t/2}b_1 + e^{-2t/3}b_2 = \left(\frac{-e^{-t/2} + e^{-2t/3}}{-e^{-t/2} + 2e^{-2t/3}}\right)$. One may check that this satisfies the DE and initial condition.

3. Solve the second-order system given by $\frac{d^2}{dt^2}x = Ax$, with initial conditions given by $x(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ and $\dot{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$.

In the *B* basis, we have $[x(0)]_B = \binom{-1}{1}$, $[\dot{x}(0)]_B = \binom{2}{-1}$, and $\frac{d^2}{dt^2} [x]_B = [A]_B [x]_B = D[x]_B$. For convenience, set $\omega_1 = \sqrt{1/2}$ and $\omega_2 = \sqrt{2/3}$. We can write down the solution $[x(t)]_B = \binom{(-1)\cos(\omega_1 t) + (2/\omega_1)\sin(\omega_1 t)}{(1)\cos(\omega_2 t) + (-1/\omega_2)\sin(\omega_2 t)}$. We then compute $x(t) = P[x(t)]_B = \binom{(-1)\cos(\omega_1 t) + (2/\omega_1)\sin(\omega_1 t) + (1)\cos(\omega_2 t) + (-1/\omega_2)\sin(\omega_2 t)}{(-1)\cos(\omega_1 t) + (2/\omega_1)\sin(\omega_1 t) + (2)\cos(\omega_2 t) + (-2/\omega_2)\sin(\omega_2 t)}$. One may check that this satisfies the initial condition (and, time permitting, the DE).

The last problem concerns $A = \begin{pmatrix} -2 & 1/2 \\ -2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1/2 & 1/4 \\ -1/2 & 1/4 \end{pmatrix}.$

4. Solve the first-order system given by $\frac{d}{dt}x = Ax$, with initial condition given by $x(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

We have a basis of generalized eigenvectors $S = \{s_1, s_2\}$, for $s_1 = (1, 2)^T$ (of order 1, hence an eigenvector), and $s_2 = (-1, 2)^T$ (of order 2). Note that $x(0) = \frac{1}{4s_1 + \frac{1}{4s_2}}$. We have $x(t) = e^{At}x(0) = e^{At}(\frac{1}{4s_1 + \frac{1}{4s_2}})$. Because s_1 is an eigenvector, $e^{At}s_1 = e^{-t}s_1$. Because s_2 is a generalized eigenvector of order 2, $e^{At}s_2 = e^{-t}(I + (A - \lambda I)t)s_2 = e^{-t}(I + (A + I)t)s_2 = e^{-t}(\frac{1-t}{-2t})s_2 = e^{-t}(\frac{t-1+t}{2t+2(1+t)}) = (\frac{e^{-t}(2t-1)}{e^{-t}(4t+2)})$. Putting it all together, we get $x(t) = \frac{1}{4}e^{-t}s_1 + \frac{1}{4}(\frac{e^{-t}(2t-1)}{e^{-t}(4t+2)}) = \frac{e^{-t}}{4}(\frac{2t}{4t+4}) = (\frac{te^{-t}/2}{(t+1)e^{-t}})$. One may check that this satisfies the DE and initial condition.